

Will Langford

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willlangford.me

EDUCATION

Massachusetts Institute of Technology, Cambridge MA *August 2012 - August 2019*
Advisor: Neil Gershenfeld — Center for Bits and Atoms Overall GPA: 5.0/5.0
Doctor of Philosophy — 2019, *Discrete Robotic Construction*: [Dissertation](#) ◊ [Defense](#)
Master of Science — 2014, *Electronic Digital Materials*: [Thesis](#)

Tufts University, Medford MA *August 2008 - May 2012*
Bachelor of Science in Mechanical Engineering Overall GPA: 3.81/4.0
Minor in Engineering Management

Honors and Awards: Vincent Manno Leadership Award, The Prize Scholarship of the Class of 1882, OLeary Design Award, Mead Jonathan Taylor Prize, Summa Cum Laude, Tau Beta Pi, Deans List (all semesters)

RESEARCH PROJECTS

A Discrete Approach to Robotic Construction *2019*
My research explored assembly-based fabrication methods that enable the construction of a wide variety of robots from a small set of millimeter-scale parts.

Digital Material Assembler *2016*
I developed an automated assembly machine that is able to build electronic components by placing individual conductive and insulating building blocks. [Project link](#)

Desktop Digital Fabrication Tools *2014 - Present*
I've designed and built a number of custom desktop-scale digital fabrication tools that I use in my research. [Desktop Wire EDM](#) ◊ [Micro-Materials Tester](#) ◊ [Punch Press](#) ◊ [Foldafab](#) ◊ [Handheld CNC](#)

Electronic Digital Materials *2014*
My masters work demonstrated and characterized the assembly of complex electronic functionality from a standardized set of conductive, insulating, resistive, and semiconducting building blocks. [Project link](#)

FODHippo: Autonomous airport runway debris removal *2012*
As my senior design project, my team and I developed and prototyped a robotic debris removal system for airport runways. We were awarded second place in FAA Design Competition for Universities. [Project link](#)

EXPERIENCE

Cardibo Inc., *Hardware Developer* *Summer 2011*
Designed a suite of wireless sensor nodes for use in gym equipment monitoring services.

Center for Engineering Education and Outreach, *R&D Associate* *2010 - 2011*
Designed a circuit board that allows Lego NXT motors and sensors connected and controlled from an Arduino microcontroller.
Developed a method of programming Arduino microcontrollers using Labview. Assisted in testing software, sourcing parts for a kid-friendly robotics kit, and web development.

Makerbot Industries, *Summer R&D Associate* *Summers 2009 - 2011*
Researched and prototyped Dual-Extrusion technologies for Makerbot 3D printers.
Designed, tested, programmed, and launched the Unicorn pen plotter tool-head.
Supported development, production, and distribution of first generation desktop 3D printers.

MIT Non-Newtonian Fluids Lab, *Research Associate* *Jan-May 2011*
Implemented control circuitry for a linear vertical stage to be used in viscosity experiments.

TECHNICAL SKILLS

Fabrication	CNC milling/turning (3/4/5-axis), wire-EDM, waterjet, laser micromachining, 3D printing (FDM, SLA), manual lathe & mill, HSMWorks, Fusion360 CAM
Imaging/Measurement	Materials strength testing (Instron), X-ray CT, SEM, confocal microscopy, 3D laser scanning
Embedded Systems	Atmel AVR (ATtiny, ATmega, Xmega), ARM, Arduino
2D/3D Design	Fusion360, Solidworks, Inventor, Rhino, Eagle, KiCad, Illustrator
Programming	Python, Javascript (incl. ThreeJS, Node, Electron), HTML, MATLAB (incl. Simulink), Labview, Excel VBA, Git

TEACHING & LEADERSHIP

Deployed [Fablabs](#) in Saudi Arabia, [Armenia](#), [Rwanda](#), and [Bhutan](#), 2014-2018

TA for [How to Make \(Almost\) Anything](#), a graduate course at MIT, 2013-2018

TA for [How to Make Something That Makes \(Almost\) Anything](#), a graduate course at MIT, 2018

TA for [The Nature of Mathematical Modeling](#), a graduate course at MIT, 2017

TA for [The Physics of Information Technology](#), a graduate course at MIT, 2016 & 2019

TA for Electronic Musical Instrument Design, an undergraduate course at Tufts University, 2011

TA for Intro to Robotics and Mechatronics, an undergraduate course at Tufts University, 2011

Founder and president of Tufts Robotics Club, 2008-2012

Director of the Tufts Botlab, a student run robotics and fabrication lab

Lead teams which placed 1st on the Trinity Firefighting Robotics Olympiad Exam twice

Granted Student Life Imagination Award for developing and conducting student robotics workshops including CNC Cupcake Frosting, Sumobot Competition, Friendly Robotics, and Toy-hacking Elmo

Mentored Medford High School and Melrose High School robotics teams

Lead teams which developed an automated hydroponics gardening systems, 12lb Battlebots for Robot Conflict competitions, and a Mars rover robot

PUBLICATIONS

Langford W, Gershenfeld N. [A Discretely Assembled Walking Motor](#), MARSS Helsinki, 2019 (**Best Student Paper Award**)

Jolly S, Savidis N, Datta B, Karydis T, Langford W, Gershenfeld N, Bove M. [Progress in fabrication of anisotropic Bragg gratings fabricated in lithium niobate via femtosecond laser micromachining](#), Proc. SPIE 10544, Advanced Fabrication Technologies for Micro/Nano Optics and Photonics XI, 2018

Langford W, Ghassaei A, Jenett B, Gershenfeld N. [Hierarchical Assembly of a Self-Replicating Spacecraft](#), IEEE Aerospace, 2017

Langford W, Ghassaei A, Gershenfeld N. [Automated Assembly of Electronic Digital Materials](#), Proceedings of the Manufacturing Science and Engineering Conference, 2016

Book Features

Designing Reality by Neil Gershenfeld, 2018

Active Matter by Skylar Tibbits, 2017

Patents

Discretely Assembled Logic Blocks, [US20190190523A1](#), *issued 2018*

Discrete Assemblers Utilizing Conventional Motion Systems, [US10155313B2](#), *issued 2018*

Self-assembling assemblers built from a set of primitive blocks, [US10155314B2](#), *issued 2018*

Electromagnetic Digital Materials, [US20140145522A1](#), *pending 2011*

SPEAKING EVENTS

[Manipulation Automation and Robotics at Small Scales \(MARSS\) Helsinki](#), Plenary Talk — *Discrete Robotic Construction*, July 2019

[Symposium on Computational Fabrication](#), *Assembly Fabrication*, June 2018

[Dimensions of Doctor Who](#), *Using Shape-Shifting Matter To Build the TARDIS*, April 2016

[FAB11 Symposium](#), *Digital Material Assembly*, August 2015

[The Science of Digital Fabrication](#), *Micro-Assembly*, May 2013

MEDIA

Tiny motor can walk to carry out tasks, [MIT News](#) ◇ [Digital Trends](#) ◇ [Techcrunch](#) 2019

Adam Savage's Maker Tour, [Tested.com](#) 2017

Fablabs, [WONDROS](#) 2016

On GPS: Future of Digital Fabrication, [CNN](#) 2013

Looking To Frost Cupcakes & Deal With the Economic Stimulus Plan? Tufts Has Some Robots For That, [BostInno](#) 2012

If you build it..., [Tufts E-News](#) 2010

Make Magazine: [Dualstrusion](#) ◇ [Bloombot](#) ◇ [Bracelets](#) ◇ [Sumobots](#) ◇ [Glasses](#) ◇ [Braille](#)

3-D Printers Make Manufacturing Accessible, [Wired](#) 2009